Inverse Stability Problem in Beam Dynamics

> Alexey Burov Fermilab

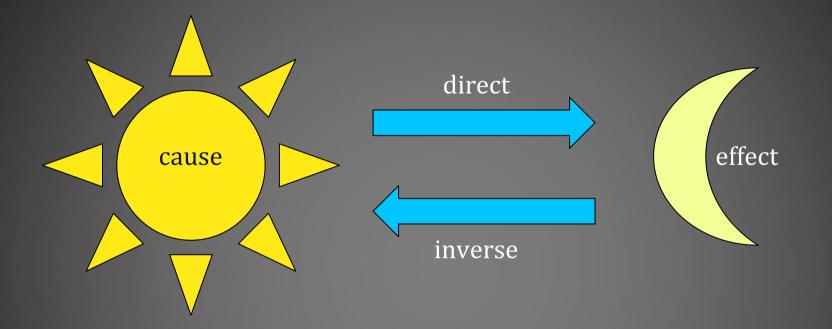
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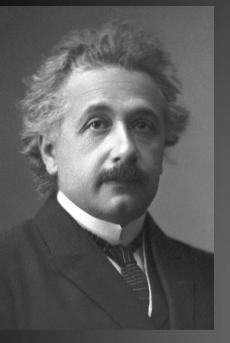
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Inverse Stability Problem in Beam Dynamics

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	Alexey Burov Phys. Rev. Accel. Beams 26 , 082801 – Published 17 August 2023						

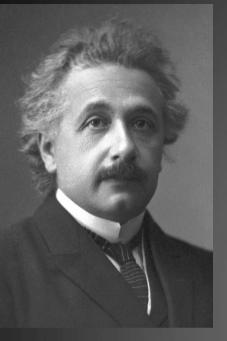
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1879-1955

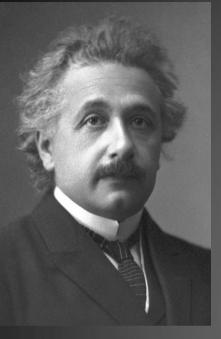
How a simplest unified description for gravity and inertia could look like? 1907–1915



1879-1955

Inverse

How a simplest unified description for gravity and inertia could look like? 1907–1915



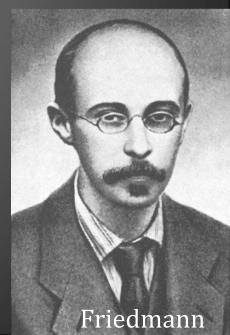
1879-1955

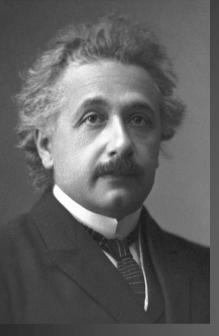
Inverse

How a simplest unified description for gravity and inertia could look like? 1907–1915

What could be a fate of the Universe, according to GR? 1922–1924

1888-1925





1879-1955

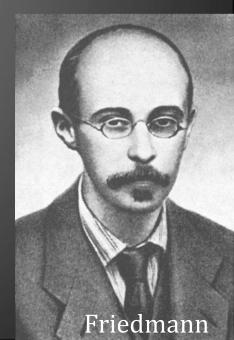
Inverse

How a simplest unified description for gravity and inertia could look like? 1907–1915

Direct

What could be a fate of the Universe, according to GR? 1922–1924

1888-1925



$$\dot{a}_k + i\Delta\omega_k a_k = -ig\bar{a}$$

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$$a_k \propto \exp(-i\nu t)$$

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$$\frac{g}{N}\sum_k \frac{1}{\nu-\Delta\omega_k} = 1$$

11

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$$\frac{g}{N}\sum_k \frac{1}{\nu - \Delta \omega_k} = 1$$

$$-\left[\int \int \mathrm{d}J_x \mathrm{d}J_y \frac{J_x \frac{\partial F}{\partial J_x}}{\nu - \Delta \omega(J_x, J_y) + io}\right]^{-1} = g$$

1D, octupoles, Gaussian

alien nonlinearity $\Delta\omega(J_x, J_y) = kJ_y \longrightarrow \left[\int dJ_y \frac{F_y(J_y)}{\nu - J_y + io} \right]^{-1} = g$

1D, octupoles, Gaussian

alien nonlinearity $\Delta\omega(J_x, J_y) = kJ_y \longrightarrow \left[\int dJ_y \frac{F_y(J_y)}{\nu - J_y + io} \right]^{-1} = g$

own nonlinearity

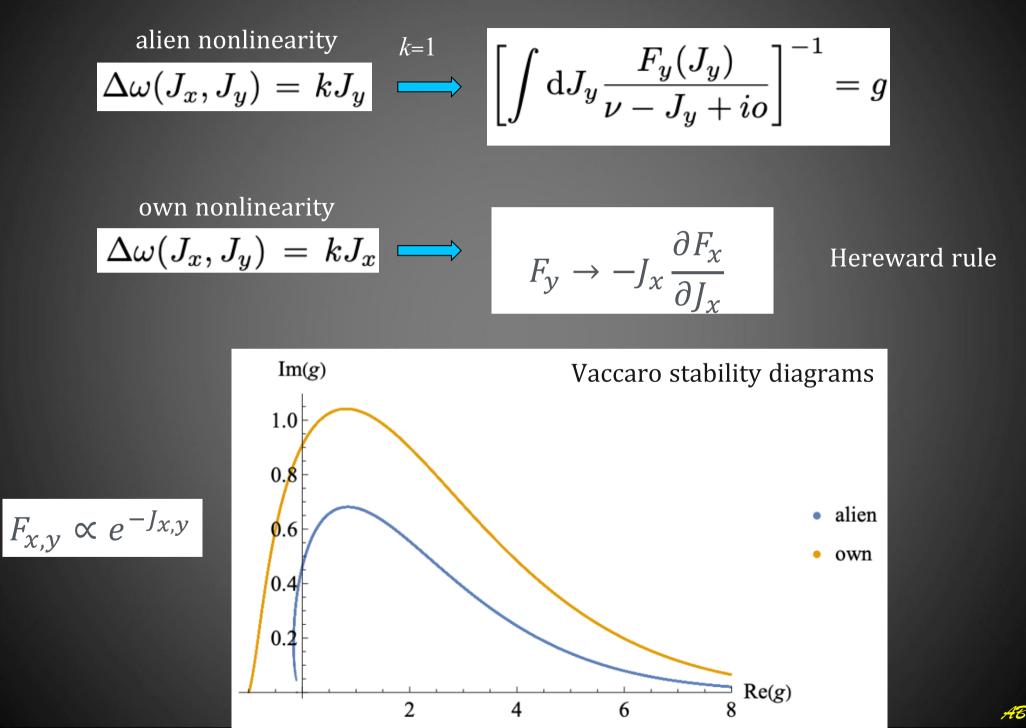
$$\Delta\omega(J_x,J_y) \,=\, k J_x \quad - \quad$$

$$F_{y} \to -J_{x} \frac{\partial F_{x}}{\partial J_{x}}$$

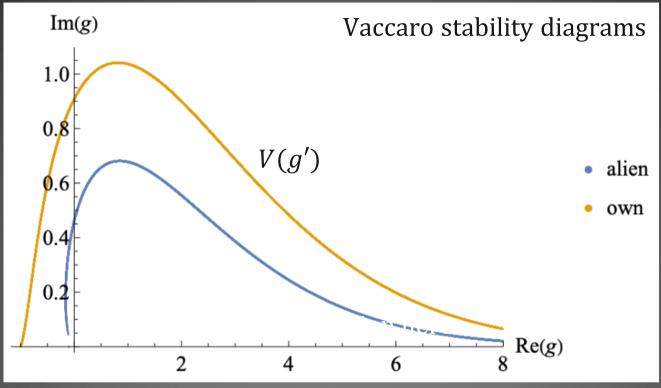
Hereward rule

AB

1D, octupoles, Gaussian



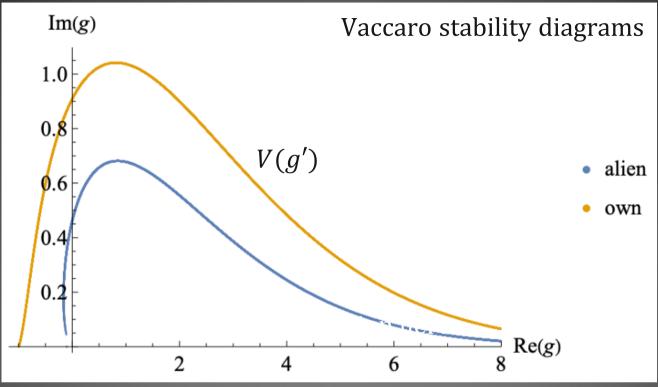
Direct and Inverse Stability Problems



Direct problem: $F(J) \rightarrow V(g')$

Inverse problem: $V(g') \rightarrow F(J)$

Direct and Inverse Stability Problems



Direct problem: $F(J) \rightarrow V(\overline{g'})$

Inverse problem: $V(g') \rightarrow F(J)$; a pair of nonlinear integral equations.

PHYSICAL REVIEW LETTERS 126, 164801 (2021)

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Proof-of-Principle Direct Measurement of Landau Damping Strength at the Large Hadron Collider with an Antidamper

S. A. Antipov⁽⁰⁾,^{1,2,*} D. Amorim⁽⁰⁾,^{1,3} N. Biancacci,¹ X. Buffat,¹ E. Métral⁽⁰⁾,¹ N. Mounet,¹ A. Oeftiger⁽⁰⁾,^{1,4} and D. Valuch⁽⁰⁾

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Tails: easy

$$\int \mathrm{d}J_y \frac{F_y(J_y)}{\nu - J_y + io} \simeq \frac{1}{\nu} - \pi i F_y(\nu)$$

$$\Re g \simeq \nu; \ \Im g \simeq \pi \nu^2 F_y(\nu)$$

$$F_y(
u) \simeq rac{\Im g(
u)}{\pi
u^2}$$

Core: fitting approach

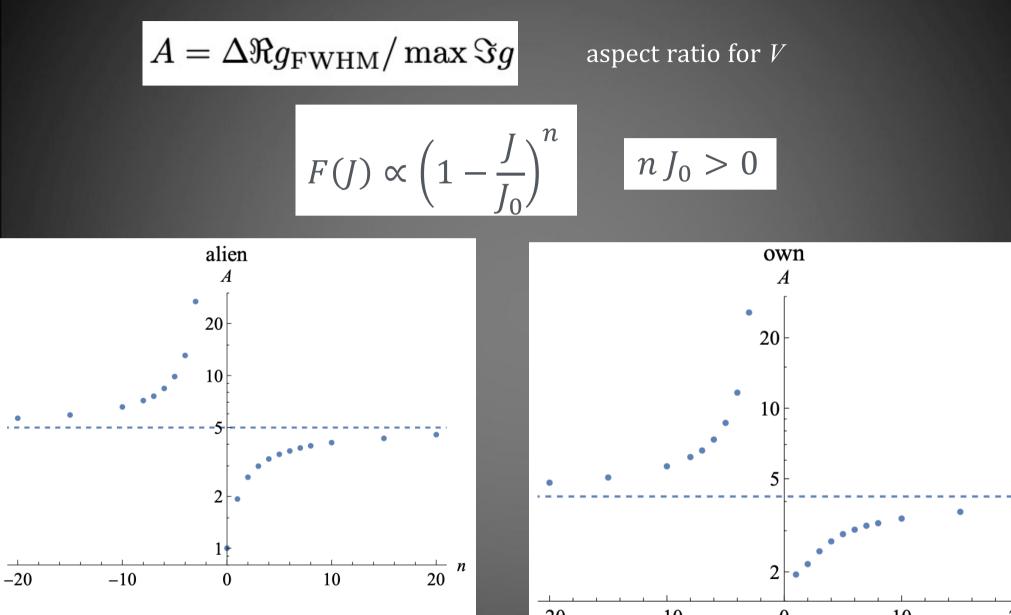
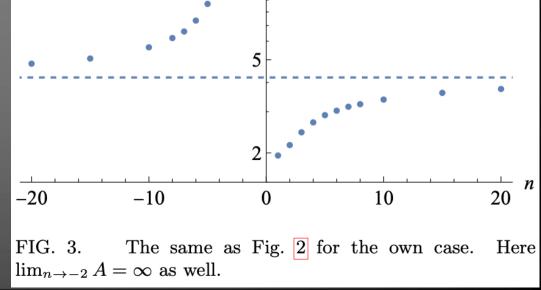


FIG. 2. Aspect ratio A of 1D stability diagram, the alien case, versus the power n of the binomial distribution function $\propto (1 - J/J_0)^n$, $nJ_0 > 0$. Note that $\lim_{n \to -2} A = \infty$. The dashed line marks the asymptote, $F(J) = J_0^{-1} e^{-J/J_0}, J_0 > 0.$



Core: iterative 4-leg walk

- 1. Compute integrals with your initial guess F(J);
- 2. With that, make tables g'(v); g''(v);
- 3. Update your guess as $F(v) = -\pi^{-1}\Im g^{-1}(v)$;
- 4. Normalize the updated F(J) and go back to 1.

Convergency Limitation

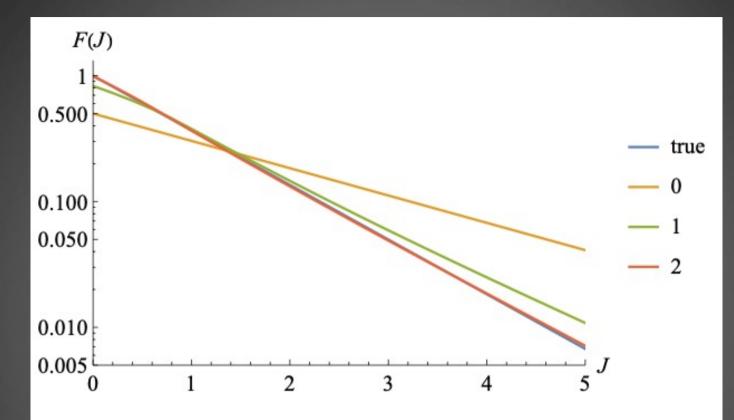


FIG. 4. An example of the iteration convergence for the alien case, $\nu_{\rm min} = 0.7$. Here "true" means the distribution responsible for the "measured diagram"; "0" means the initial guess of the distribution, while "1" and "2" stand for the output distributions after the first and second four-leg moves of the algorithm. The latter is clearly very fast, but it becomes unstable at small actions, $J \leq 0.5$, for a slightly smaller border $\nu_{\rm min}$.

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2D case $\Delta \omega(J_x, J_y) = k_x J_x - k_y J_y$

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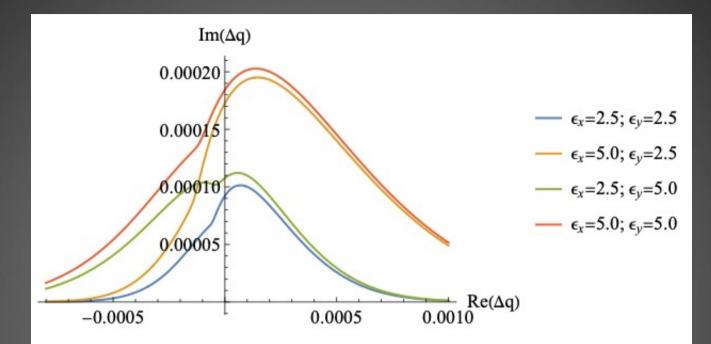


FIG. 7. Vaccaro diagrams calculated for a Gaussian bunch at the LHC top energy for 550A of the octupole current, yielding $k_x = 1.0 \cdot 10^{-4}$, $k_y = 0.7 \cdot 10^{-4}$ for the normalized rms emittances 2.5mm·mrad; for more details see Ref. [5]. Gaussian normalized rms emittances for each curve are shown.

Positive tune shifts mostly correspond to *x*, negative — to *y*. The problem is effectively factorized, reducing to 1D case.

Chromaticity effects

If $|g| \ll \omega_s$ then the gain is distributed between the headtail modes:

$$g \rightarrow g_l = g \ K_l(\zeta)$$
 with ζ = rms HT phase

 $K_l(\zeta) = \exp(-\zeta^2) \mathrm{I}_l(\zeta^2)$ for the longitudinally Gaussian case

 $K_l = \int_0^\infty {
m J}_l^2(\zeta r) f(r) r {
m d} r$ in general

$$\sum_{l=-\infty}^{\infty} K_l = 1$$

If $|g| \gg \omega_s$, $|\zeta|\omega_s$, the single rigid–bunch mode is formed, taking the entire gain.

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Many thanks!