

Xobjects and Xdeps: Low-Level Libraries Empowering Beam Dynamics Simulations

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Xsuite – A Beam Dynamics Simulation Package [1]

- As a **Python** package, it is easy to use and flexible.
- Fast and extensible, since critical parts are in **C**.
- ► Multi-threading on CPU (OpenMP [2]), GPU (CUDA [3], OpenCL [4]).
- Imports from MAD-X, includes expressions.

Powered by **Xobjects** and **Xdeps**.

Xobjects – An In-Memory Serialiser

Writing portable GPU-accelerated code is non-trivial.

With Xobjects, write code once.

Xdeps – A Data Dependency Manager and Optimiser

Implement MAD-X deferred expressions (a := b) in Xsuite.

- Declare variables and their dependencies.
- Keep values updated based on the dependencies.

An optimiser module used for optics matching.

Design

Xdeps can be used to update **any Python object**. Key concepts:

- Manager register external objects, orchestrate actions.
- Task describes an action that modifies the values of targets according to a set of dependencies, and potentially its internal state.
 Expression represents a generic Python expression between different values. Can define a task when an expression of references is assigned to another reference.

- Support single- and multi-threading.
- ► OpenMP, CUDA, OpenCL.

Specify **portable binary objects** for the code.

- Accessible from Python and C.
- Standard numeric types supported.
- Multi-dimensional arrays with any strides, fixed/dynamic shapes.
- Compound types: structs, unions, etc.

An Xobject Example

Represent an array of \mathbb{R}^2 vectors:

```
1 import xobjects as xo
```

```
2
```

```
3 class Vectors(xo.Struct):
```

- 4 x = xo.Float64[:]
- 5 y = xo.Float64[:]
- Instantiate and access an Xobject from Python:
- 6 vec = Vectors(x=[1, 2], y=[3, 4])

An Xdeps Example

Set-up: convert Cartesian to planar coordinates.

```
1 import xdeps as xd, math
2 from types import SimpleNamespace
3
4 pt = SimpleNamespace(x=1, y=1)
5
6 # Set up manager and reference
7 mgr = xd.Manager()
8 pt_ = mgr.ref(pt, 'pt')
9 math_ = mgr.ref(math, 'math')
10
11 # Define expression-based tasks
12 pt_.r = math_.sqrt(pt_.x**2 + pt_.y**2)
13 pt_.th = math_.atan2(pt_.y, pt_.x)
```

```
7 vec.x.to_nparray() #=> np.array([1, 2])
```

- > Xobjects will generate a C API, for defining accelerated functions:
- 1 int64_t Vectors_len_x(Vectors obj);
- 2 double Vectors_get_x(const Vectors obj, int64_t i0);
- 3 double Vectors_set_x(
- 4 const Vectors obj,
- 5 int64_t i0,
- 6 double value);
- 7 // etc...
- With the API own functions can be defined, e.g. we can calculate lengths of element vectors in parallel (ArrayNFloat64 = xo.Float64[:]):

```
1 /*gpufun*/ void get_lengths(
```

```
2 VectorsData v,
```

```
3 ArrayNFloat64 result
```

```
4){
```

14 }

- 5 int64_t n = Vectors_len_x(p);
- $6 \quad int 64_t = 0;$
- //vectorize_over i n
- 8 double x, y, l;

```
9 x = Vectors_get_x(v, i);
```

```
10 y = Vectors_get_y(v, i);
```

```
11  l = sqrt(x*x + y*y);
```

• Updating *x* recomputes *r* and θ :

14 pt_.x = 0
15 print(pt.x, pt.r, pt.th) #=> (0, 1.0, pi/2)

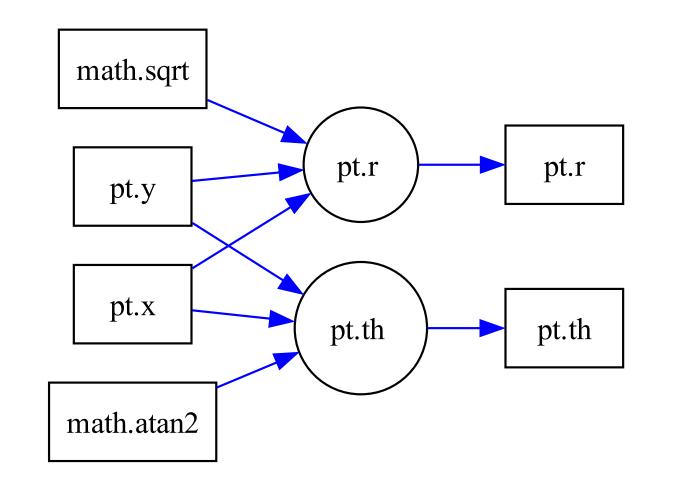


Figure 1: The graph of expressions (boxes)
which are dependencies and targets of tasks
(circles). Can be plotted with
mgr.plot_deps().

An Optimiser Suited for Fine-Tuning

- ► Tried-and-tested Jacobian optimiser of MAD-X [5].
- To start, specify target conditions, tolerances, weights, and parameters to vary; defaults can be given.
- Match typically against Twiss, but any observable can be chosen.
- A summary of the match results can be printed, and a log of the iteration steps is available.

- 11 ArrayNFloat64_set(result, i, l);
 13 //end_vectorize
- ► The decorations tell Xobjects how to parallelise the code.

Use in Particle Tracking

- Non-collective line elements have parallelisable tracking functions.
 Track sections of the beam line in parallel, or in sequence, as needed.
- Portability: data can easily move between CPU and GPU contexts.
- Creating own elements is as simple as subclassing, no knowledge of internals needed!

- The match state can be rolled back, and targets or parameters can be enabled or disabled.
- **Single steps** of the match can be executed, if necessary.

References

- [1] G. Iadarola, et al., Xsuite: An Integrated Beam Physics Simulation Framework. *Proceedings of the 68th ICFA ABDW on High-Intensity and High-Brightness Hadron Beams*, Geneva, Switzerland, 2023.
- [2] L. Dagum and R. Menon, OpenMP: An Industry Standard API for Shared-Memory Programming. *IEEE Computational Science and Engineering*, 5(1):pp. 46–55, 1998.
- [3] J. Nickolls, et al., Scalable Parallel Programming with CUDA. ACM SIGGRAPH 2008 Classes, pp. 1–14, ACM, Los Angeles California, 2008.
- [4] J. E. Stone, D. Gohara, and G. Shi, OpenCL: A Parallel Programming Standard for Heterogeneous Computing Systems. *Computing in Science & Engineering*, 12(3):pp. 66–73, 2010.
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xsuite.web.cern.ch

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